

V Webinar 2022

05 de julho de 2022 às 14h00.

The New Wave in Robot Grasping

Canal do Youtube da SBA

Abstract: Despite 50 years of research, robots remain remarkably clumsy, limiting their reliability for warehouse order fulfillment, robot-assisted surgery, and home decluttering. The First Wave of grasping research is purely analytical, applying variations of screw theory to exact knowledge of pose, shape, and contact mechanics. The Second Wave is purely empirical: end-to-end hyperparametric function approximation (aka Deep Learning) based on human demonstrations or time-consuming self-exploration. A "New Wave" of research considers hybrid methods that combine analytic models with stochastic sampling and Deep Learning models. I'll present this history with new results from our lab on grasping diverse and previously-unknown objects.



Biografia do palestrante:

Kenneth Yigael Goldberg is an American artist, writer, inventor, and researcher in the field of [robotics](#) and [automation](#). He is professor and chair of the [industrial engineering and operations research](#) department at the [University of California, Berkeley](#), and holds the William S. Floyd Jr. Distinguished Chair in Engineering at Berkeley, with joint appointments in Electrical Engineering and Computer Science (EECS), Art Practice, and the School of Information. Prof. Goldberg also holds an appointment in the Department of Radiation Oncology at the [University of California, San Francisco](#).

Prof. Goldberg and his students have published over 170 peer-reviewed technical papers on algorithms for [Robotics](#), [Automation](#), and social information filtering. Prof. Goldberg leads the UC Berkeley Automation Sciences Lab, which pursues research in Cloud Robotics and Automation, Social Information Retrieval using geometric algorithms, and Algorithmic Automation for Feeding, Fixturing, Grasping, with an emphasis on geometric algorithms that minimize sensing and actuation.

For his research, Goldberg was awarded the [National Science Foundation](#) Young Investigator Award in 1994, the [National Science Foundation](#) Presidential Faculty Fellowship in 1995, the [Joseph F. Engelberger](#) Robotics Award in 2000, the [IEEE](#) Major Educational Innovation Award in 2001. Goldberg was named [IEEE Fellow](#) in 2005 "for contributions to networked telerobotics and geometric algorithms for automation."

Apoio: *Diretoria SBA*